

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L6	455	703/8.ccls.	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/16 18:30

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L3	1617	(280/5.5\$).ccls. and @ad<"20020101"	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/16 17:22
L4	0	(280/5.5\$).ccls. and @ad="20020101"	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/16 18:03
L5	486	(280/5.5\$).ccls. and @ad>"20020101"	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/16 18:03

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L13	2	(stewart adj platform and spring).clm.	US-PGPUB	OR	OFF	2008/05/16 19:36
L14	1	(parallel adj kinematic and spring).clm.	US-PGPUB	OR	OFF	2008/05/16 19:38
L15	2	(six near degree and spring).clm.	US-PGPUB	OR	OFF	2008/05/16 19:38
L16	1	(six near freedom and spring).clm.	US-PGPUB	OR	OFF	2008/05/16 19:38
L17	1	((six near freedom) and spring).clm.	US-PGPUB	OR	OFF	2008/05/16 19:40
L18	50	(six near degree\$1 and spring).clm.	US-PGPUB	OR	OFF	2008/05/16 19:40
L19	1	(six near freedom and spring\$1).clm.	US-PGPUB	OR	OFF	2008/05/16 19:43
L20	1	((six near freedom) and spring\$1).clm.	US-PGPUB	OR	OFF	2008/05/16 19:45
L21	47	((six near5 freedom) and spring\$1).clm.	US-PGPUB	OR	OFF	2008/05/16 19:45

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L4	576	(six near degree near freedom) and @ad<"20020101"	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/16 14:13
L5	89	L4 and (automobile or suspension or shock or damper)	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/16 14:13
L6	101	(stewart near platform) and @ad<"20020101"	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/16 14:26
L8	27	L6 and (automobile or suspension or shock or damper)	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/16 14:27

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Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L10	64	stewart adj platform and spring	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/16 19:15
L11	24	stewart adj platform and suspension	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/16 19:22
L12	96	parallel adj kinematic\$1 and @ad<"20020101"	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/16 19:24

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Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L24	535	(six near degree\$1 near freedom) and (automobile or suspension or damper) and @ad<"20020101"	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/16 19:50

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L2	3	(spring near design) and (parallel near mechanism) and @ad<"20020101"	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/18 15:28
L3	0	(spring near design) and (stewart near mechanism) and @ad<"20020101"	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/18 15:29
L4	0	(spring near design) and (stewart near platform) and @ad<"20020101"	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/18 15:29

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	66	(hydraulic same actuator) same (force near sensor) and @ad<"20020101"	US-PGPUB; USPAT; EPO; DERWENT	OR	OFF	2008/05/18 17:00



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A six degree-of-freedom wrist with pneumatic suspension

SE Salcudean, S Bachmann, D Ben-Dov - Robotics and Automation, 1994. Proceedings., 1994 IEEE ..., 1994 -
ieeexplore.ieee.org

... of using them in a con- ventional **Stewart platform arrangement** ... mm (0.25 in) I I Bellows

Spring Rate I ... hystere- sis in the mechanism is the flexural **suspension**. ...

Cited by 4 - Related Articles - Web Search - BL Direct

A study of the effects of the lower index methods on ADAMS sparse tableau formulation for the
... - all 4 versions »

NV Orlandea - Proceedings of the Institution of Mechanical Engineers, Part ..., 1999 - journals.pepublishing.com

... The **suspension** has a **spring** and a damper not shown in Fig. 8 for reason of clarity.

As before, for this system the violation of the constraint Fig. ...

Cited by 4 - Related Articles - Web Search

[PS] Development of the NIST Robot Crane Teleoperation Controller - all 2 versions »

NG Dagalakis, JS Albus, RV Bostelman, J Fiala - Robotics and Remote Handling Proceedings, Fifth Topical ...,
1993 - isd.mel.nist.gov

... joystick was another small size **Stewart platform** mechanism shown in ... applied to a

steel leaf **spring** plate mounted ... the coordinates of the **suspension** points, with ...

Cited by 5 - Related Articles - View as HTML - Web Search

Design analysis of a Stewart platform for vehicle emulator systems

Y Gong - 1992 - dspace.mit.edu

... geometric parameters of **Stewart platform** due to imperfect assembly and ... For

VES to simulate more general base system, eg, the **suspension** ...

Cited by 1 - Related Articles - Web Search

[PDF] Applications of the NIST RoboCrane - all 3 versions »

R Bostelman, J Albus, N Dagalakis, A Jacoff, J ... - Proceedings of the 5th International Symposium on Robotics
..., 1994 - isd.mel.nist.gov

... tubular gantry, containing three upper **suspension** points for ... **Stewart Platform** Joystick

Figure 2 - Robocrane Control System ... plate that acted as a leaf-**spring**. ...

Cited by 20 - Related Articles - View as HTML - Web Search

[CITATION] THE DESIGN AND IMPLEMENTATION OF A LABORATORY TEST BED FOR

SPACE ROBOTICS: THE VES MOD II Steven ...

U Muller, I Paul, M Cambridge, J Pennington, AT ... - Robotics: Kinematics, Dynamics and Controls: Presented at
..., 1994 - American Society of Mechanical Engineers

Related Articles - Web Search

Experimental Simulation of Manipulator Base Compliance - all 7 versions »

H West, N Hootsmans, S Dubowsky, N Stelman - Proceedings of the First International Symposium on ..., 1989 -
Springer

... **Stewart Platform** ... The model used by the emulator was for a vehicle whose
suspension consisted of a combination of **springs** and dampers. ...

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"stewart platform" spring automobile

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Modeling, simulation, and control of a hydraulic Stewart platform

D Li, SE Salcudean - Robotics and Automation, 1997, Proceedings, 1997 IEEE ..., 1997 - [ieeexplore.ieee.org](#)
... control of the **Stewart platform** based vehicle emulation system ... For the **Stewart platform** considered here, the mass of ... fric- tion), K is the **spring** constant of ...

Cited by 39 - Related Articles - Web Search - BL Direct

Experimental study of motion control and trajectory planning for a Stewart Platform robot manipulator

CC Nguyen, SS Antrazi, ZL Zhou, CE Campbell Jr - Robotics and Automation, 1991, Proceedings, 1991 IEEE ..., 1991 - [ieeexplore.ieee.org](#)

... Six **spring**-loaded pistons arranged also in a geometry similar to the **Stewart Platform** mech- anism are used to suspend the lower compliant plat- form from the ...

Cited by 13 - Related Articles - Web Search

Development of the PNU vehicle driving simulator and its performance evaluation - all 2 versions »

MK Park, MC Lee, KS Yoo, K Son, WS Yoo, MC Han - Robotics and Automation, 2001, Proceedings 2001 ICRA, IEEE ..., 2001 - [ieeexplore.ieee.org](#)

... Simulator Studies: The Influence of Vehicle Parameters on ... [9] E. F. Fichter, "A **Stewart Platform**-based Manipulator ... of the KSME 1998 **Spring** Annual Meeting A, ...

Cited by 7 - Related Articles - Web Search - BL Direct

Force guided assemblies using a novel parallel manipulator - all 3 versions »

DM Morris, R Hebbbar, WS Newman - Robotics and Automation, 2001, Proceedings 2001 ICRA, IEEE ..., 2001 - [ieeexplore.ieee.org](#)

... four assembly examples from **automotive** automatic transmissions ... Research, Vol6, No 1, **Spring** 1987, pp 3 ... Arai, T., "A Modified **Stewart Platform** Manipulator with ...

Cited by 8 - Related Articles - Web Search - BL Direct

Stewart-platform-based inlet duct painting system

K Liu, R Gienn, TJ Lawley, FL Lewis - Robotics and Automation, 1993, Proceedings, 1993 IEEE ..., 1993 - [ieeexplore.ieee.org](#)

... 93 \$3.00 © 1993 IEEE 106 **Stewart-Platform**-Based Inlet ... MORGER is an autonomous three wheeled vehicle capable of ... a rather ingenious design of **springs** and levers ...

Cited by 3 - Related Articles - Web Search - BL Direct

KAIST interactive bicycle simulator - all 13 versions »

DS Kwon, GH Yang, CW Lee, JC Shin, Y Park, B Jung, ... - Robotics and Automation, 2001, Proceedings 2001 ICRA, IEEE ..., 2001 - [ieeexplore.ieee.org](#)

... processors for digital servo control of the **Stewart platform** have been ... the bicycle is a two-wheeled vehicle, it can ... we model the tire as a **spring**-damper system ...

Cited by 21 - Related Articles - Web Search - BL Direct

Design analysis of a Stewart platform for vehicle emulator systems

Y Gong - 1992 - [dSPACE.mit.edu](#)

... tfr 4' < ,tfr : I- STITUTE F.B 0o 199 UtJRAIE5 ARC-JI ,,: Page 2. DESIGN ANALYSIS OF A **STEWART PLATFORM** FOR VEHICLE EMULATOR SYSTEMS by YUHHONG GONG ...

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"stewart platform" spring design

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Design and control of a simplified Stewart platform for endoscopy - all 3 versions »

JM Wendlandt, SS Sastry - Decision and Control, 1994., Proceedings of the 33rd IEEE ..., 1994 -
ieeexplore.ieee.org

... The **design** shares simi- larities with the **Stewart Platform** but has ... do not need the
full motion of the **Stewart platform** ... by rigid tubes and a **spring**-like device ...

Cited by 14 - Related Articles - Web Search - BL Direct

Design and development of a Stewart platform based force-torque sensor - all 2 versions »

TA Dwarakanath, B Dasgupta, TS Mruthyunjaya - Mechatronics, 2001 - Elsevier
... analysed a similar structure and enumerated a **few design** criteria for the sensor
structure. The concept of a passive **Stewart platform** with **spring** loaded legs ...

Cited by 21 - Related Articles - Web Search

The Stewart platform manipulator: a review - all 4 versions »

B Dasgupta, TS Mruthyunjaya - Mechanism and Machine Theory, 2000 - Elsevier
... analysed a similar structure and enumerated a **few design** criteria for the sensor
structure. The concept of a passive **Stewart platform** with **spring**-loaded legs ...

Cited by 181 - Related Articles - Web Search - BL Direct

Dynamic analysis and control of a Stewart platform manipulator - all 3 versions »

G Lbret, K Liu, FL Lewis - J ROB SYST, 1993 - doi.wiley.com

Page 1. Dynamic Analysis and Control of a **Stewart Platform** Manipulator ... In this article,
we study the dynamic equations of the **Stewart platform** manipulator. ...

Cited by 99 - Related Articles - Web Search - BL Direct

Closed-form force sensing of a 6-axis force transducer based on the Stewart platform - all 3
versions »

CG Kang - Sensors & Actuators: A. Physical, 2001 - Elsevier

... Let the **spring** constant of **springs** mounted on the legs to be 87.5 N/mm, and the
maximum ... The **design** parameters of the **Stewart platform** were selected in ...

Cited by 23 - Related Articles - Web Search

Modeling, simulation, and control of a hydraulic Stewart platform

D Li, SE Salcudean - Robotics and Automation, 1997. Proceedings., 1997 IEEE ..., 1997 - ieeexplore.ieee.org

... For the **Stewart platform** considered here, the mass of the six legs is considerably ...
coefficient (normally piston seal fric- tion), K is the **spring** constant of ...

Cited by 39 - Related Articles - Web Search - BL Direct

A six degree of freedom micromanipulator for ophthalmic surgery

KW Grace, JE Colgate, MR Glucksberg, JH Chun - Robotics and Automation, 1993. Proceedings., 1993 IEEE ...,
1993 - ieeexplore.ieee.org

... the physical **design** of a **Stewart Platform** can be divided into two classes: (I) legs
either pull or push against an antagonistic force (ie a **spring** pushes the ...

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Genetic design of kinematically optimal fine tuning Stewart platform for large spherical radio
... - all 2 versions »



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"stewart platform" "spring design"

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[Geometric Analysis of Antagonistic Stiffness in Redundantly Actuated Parallel Mechanisms](#) - all 3 versions »

RA Freeman - Journal of Robotic Systems, 1993 - doi.wiley.com

... Hogan2' modeled equilibrated axes consisting of **passive springs** and discussed the concept of open-loop disturbance rejection and nonlin- ear **spring design**. ...

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[Static balancing of 3-DOF planar parallel mechanisms](#) - all 3 versions »

T Laliberte, CM Gosselin, M Jean - Mechatronics, IEEE/ASME Transactions on, 1999 - ieeexplore.ieee.org

Page 1. IEEE/ASME TRANSACTIONS ON MECHATRONICS, VOL. 4, NO. 4, DECEMBER 1999

363 Static Balancing of 3-DOF Planar Parallel Mechanisms ...

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[\[BOOK\] Robotics and Manufacturing: Recent Trends in Research, Education, and Applications: Proceedings of ...](#)

M Jamshidi - 1992 - Amer Society of Mechanical

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[\[PDF\] Development and demonstration of a teleoperated modular robot system. BI-monthly progress report. ...](#) - all 2 versions »

S Tosunoglu, D Tesar - 1992 - osti.gov

... architecture for active **spring design**. ... A redundantly actuated **Stewart platform**-type manipulator has been studied as an illustrative example. ...

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... architecture for active **spring design**. ... A redundantly actuated **Stewart platform**-type manipulator has been studied as an illustrative example. ...

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[\[BOOK\] Fundamentals of Robotics](#)

DD Ardayio - 1987 - books.google.com

... **Spring Design** with an IBM PC, by AI Dietrich Mechanical Design Failure Analysis: With Failure Analysis System ... **Stewart Platform** Based on Regular Octahedron ...

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[\[CITATION\] TOWARD AUTOMATION OF PATIENT-SPECIFIC FINITE ELEMENT MODELS FOR BONE GRAFTING OF FEMORAL HEAD ...](#)

MJ Rudert, TD Brown - Advances in Bioengineering, 1971 - American Institute of Chemical Engineers

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[\[CITATION\] A Simplified Multi-Input Multi-Output Formulation for the Quantitative Feedback Theory](#)

Y Chait - Journal of Dynamic Systems, Measurement, and Control, 1971 - American Society of Mechanical Engineers



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[CITATION] ACTIVE SPRING DESIGN VIA REDUNDANTLY ACTUATED PARALLEL
MECHANISMS

RA Freeman - Robotics and Manufacturing: Recent Trends in Research, ..., 1992 - Amer Society of Mechanical
Related Articles - Web Search

Analysis for a planar 3 degree-of-freedom parallel mechanism with actively adjustable stiffness ...

WK Kim, JY Lee, BJ Yi - Robotics and Automation, 1997. Proceedings., 1997 IEEE ..., 1997 - [ieeexplore.ieee.org](#)
... approach, it is achieved by **antagonistic** redundant actuation ... first- and second-order
kinematic **analysis** for the ... the compliance matrix, the **stiffness** matrix in ...

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Optimization of the antagonistic stiffness characteristic of a five-bar mechanism with redundant ...

SH Lee, BJ Yi, SH Kim, YK Kwak - Intelligent Robots and Systems, 1999. IROS'99. Proceedings. ..., 1999 -
[ieeexplore.ieee.org](#)

... The **redundantly actuated** system can produce proper internal ... with complex nonlinear
geometry of the ... The **antagonistic stiffness** can be modulated arbitrarily by ...

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Analysis of a 5-bar finger mechanism having redundant actuators with applications to stiffness and ...

BJ Yi, IH Suh, SR Oh - Robotics and Automation, 1997. Proceedings., 1997 IEEE ..., 1997 - [ieeexplore.ieee.org](#)
... **Analysis of A 5-bar Finger Mechanism Having ...** system to modulate the end-point **stiffness**
or motion ... via internal loads in **redundantly actuated** closed chain systems ...

[Web Search](#)

Frequency modulation in anthropomorphic robots with kinematic and force redundancies

BJ Yi, SR Oh, IH Suh, WK Kim - Robotics and Automation, 1998. Proceedings. 1998 IEEE ..., 1998 -
[ieeexplore.ieee.org](#)

... impedance property comes from the **antagonistic** activation of ... to deal with our further
analysis of the ... of F_d remains constant, the effective **stiffness** matrix $[K ...$

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Feedforward modulation of dynamic behaviour in anthropomorphic robots via force redundancies - all 2 versions »

BJ Yi, JH Lee - Robotics and Automation, 1999. Proceedings. 1999 IEEE ..., 1999 - [ieeexplore.ieee.org](#)
... **analysis** and design of **redundantly actuated** linkage systems [2 ... restricted to modulation
and **analysis** of stiffness ... system to modulate the **stiffness** property or ...

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[CITATION] Byung-Ju Yi and Whee Kuk Kim

ASP MANIPULATOR - Mobile Robot Technology: A Proceedings Volume from the IFAC ..., 2001 - Pergamon

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Static balancing of 3-DOF planar parallel mechanisms - all 3 versions »

T Laliberte, CM Gosselin, M Jean - *Mechatronics, IEEE/ASME Transactions on*, 1999 - [ieeexplore.ieee.org](#)
... of the Mechanisms For each type of **planar parallel mechanism** introduced in ... and for
the mechanisms with **springs**—can be thought of as the **design** space, in ...

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Design, analysis, and control of a low power joint for walking robots, by phasic activation of ... - all 3 versions »

RQ van der Linde - *Robotics and Automation, IEEE Transactions on*, 1999 - [ieeexplore.ieee.org](#)
... **Design Automat.**, vol ... Y.Imamura, "An instrumented compliant wrist using a **parallel mechanism**," *Proc ...*, 17, T. A.McMahon, "Spring-like properties of muscles and ...

Cited by 41 - [Related Articles](#) - [Web Search](#) - [BL Direct](#)

Geometric Analysis of Antagonistic Stiffness in Redundantly Actuated Parallel Mechanisms - all 3 versions »

RA Freeman - *Journal of Robotic Systems*, 1993 - [doi.wiley.com](#)
... disturbance rejection and nonlin- ear **spring design**. ... antagonism generated from preloaded
passive springs. ... of a "fully **parallel**" mechanism consisting of R, N ...

Cited by 22 - [Related Articles](#) - [Web Search](#) - [BL Direct](#)

[CITATION] Eclipse: An overactuated parallel mechanism for rapid machining

SJ Ryu, JW Kim, JC Hwang, C Park, HS Cho, K Lee, Y ... - 1998 *ASME International Mechanical Engineering Congress and ...*, 1998

Cited by 31 - [Related Articles](#) - [Web Search](#) - [BL Direct](#)

Virtual model control of a bipedal walking robot - all 15 versions »

J Pratt, P Dilworth, G Pratt - *Robotics and Automation*, 1997. *Proceedings.*, 1997 *IEEE ...*, 1997 - [ieeexplore.ieee.org](#)

... for each serial link of this **parallel mechanism** in the ... third constraint provides
us with a **design de- gree** ... Figure 3: **Spring Turkey**, our bipedal walking robot. ...

Cited by 124 - [Related Articles](#) - [Web Search](#) - [BL Direct](#)

Static Balancing of Spatial Parallel Platform Mechanisms—Revisited - all 2 versions »

I Ebert-Uphoff, CM Gosselin, T Laliberte - *Journal of Mechanical Design*, 2000 - [link.aip.org](#)
... recently been introduced to the **design** of robotic ... Kumar discuss the use of **springs**
for gravity ... balancing of a planar **parallel mechanism** using counterweights or ...

Cited by 16 - [Related Articles](#) - [Web Search](#) - [BL Direct](#)

On the design of gravity-compensated six-degree-of-freedom parallel mechanisms

CM Gosselin, J Wang - *Robotics and Automation*, 1998. *Proceedings.* 1998 *IEEE ...*, 1998 - [ieeexplore.ieee.org](#)
... a more general perspective, the **design** of a ... which is statically balanced using **springs**
will be ... spatial six-degree-of- freedom **parallel mechanism** with revolute ...

Cited by 10 - [Related Articles](#) - [Web Search](#) - [BL Direct](#)

[PDF] Design and evaluation of a high-performance haptic interface - all 6 versions »

RE Ellis, OM Ismaeil, MG Lipsett - *Robotica*, 1996 - [cs.queensu.ca](#)

... possible to produce a fully **parallel mechanism** with six ... force measurements indicated



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"parallel mechanism" "spring design"

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Static balancing of 3-DOF planar parallel mechanisms - all 3 versions »

T Laliberte, CM Gosselin, M Jean - Mechatronics, IEEE/ASME Transactions on, 1999 - ieeexplore.ieee.org

... Index Terms—Dynamics, **parallel mechanism**, static balancing. ... A. Eight-Bar

Mechanism A planar 3-DOF **parallel mechanism** is shown in Fig. ...

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RA Freeman - Journal of Robotic Systems, 1993 - doi.wiley.com

... the concept of open-loop disturbance rejection and nonlin- ear **spring design**. ... is

illustrated here in terms of a "fully **parallel**" **mechanism** consisting of R ...

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Elastic actuator for precise force control - all 3 versions »

GA Pratt, MM Williamson - US Patent 5,650,704, 1997 - freepatentsonline.com

... et al., "An instrumented compliant wrist using a **parallel mechanism**," Japan/USA ... springs

are too efficient, ie, a given cylindrical **spring design** that attains a ...

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[CITATION] **ACTIVE SPRING DESIGN VIA REDUNDANTLY ACTUATED PARALLEL MECHANISMS**

RA Freeman - Robotics and Manufacturing: Recent Trends in Research, ..., 1992 - Amer Society of Mechanical

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Design of multi-degree-of-freedom spring mechanisms: biomimetic approach

BJ Yi, JH Lee, WK Kim, IH Suh - Intelligent Robots and Systems, 2000.(IROS 2000). ..., 2000 -

ieeexplore.ieee.org

... In the above five categories, previous **spring design** has been task-specific with

the systems unable to actively control (adjust) the spring rate independent of ...

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S Tosunoglu, D Tesar - 1992 - osti.gov

... springs. Initially, a planar **parallel mechanism** is employed to simulate the spring

behavior by redundant actuation. ... architecture for active **spring design**. ...

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Simultaneous stiffness generation and internal load distribution inredundantly actuated mechanisms

BJ Yi, RA Freeman - Advanced Robotics, 1991.'Robots in Unstructured Environments ..., 1991 -

ieeexplore.ieee.org

... the concept of open-loop disturbance rejection and nonlinear **spring design**. ... 4] designed

an active wrist, which has a **parallel mechanism** structure composed of ...

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 T Laliberte, CM Gosselin, M Jean - *Mechatronics, IEEE/ASME Transactions on*, 1999 - [ieeexplore.ieee.org](#)

 ... Index Terms—Dynamics, **parallel mechanism**, static balancing. ... A. Eight-Bar

Mechanism A planar 3-DOF **parallel mechanism** is shown in Fig. ...

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 RA Freeman - *Journal of Robotic Systems*, 1993 - [doi.wiley.com](#)

 ... the concept of open-loop disturbance rejection and nonlin- ear **spring design**. ... of

 a kinematic modeling methodology for general serial and **parallel mechanisms**. ...

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[Design, fabrication, and real-time neural network control of athree-degrees-of-freedom ... - all 5 versions »](#)

 SS Ku, U Pinoson, S Cetinkunt, S Nakajima - *Mechatronics, IEEE/ASME Transactions on*, 2000 - [ieeexplore.ieee.org](#)

 ... con- sisting of a pair of **parallel** springs where 2 ... is designed as a leaf-spring

mechanism (Fig. ... is converted to tool displacement through a leaf-spring design. ...

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[\[PDF\] Learning by single function agents during spring design - all 2 versions »](#)

 DL Grecu, DC Brown - *Artificial Intelligence in Design*, 1996 - [cs.wpi.edu](#)

 ... of material selection in **Spring design** is described ... **Parallel** decompositions allow

 opportunistic collabo- ration ... Although a scheduling **mechanism** is required for ...

 Cited by 24 - [Related Articles](#) - [View as HTML](#) - [Web Search](#)
[Agent-Based Synthesis of Electromechanical Design Configurations - all 6 versions »](#)

 MI Campbell, J Cagan, K Kotovsky - *Journal of Mechanical Design*, 2000 - [link.aip.org](#)

 ... to connect embodiments in **parallel** or series. ... the design evaluation **mechanism**, design

 sorter ... Function Agents During **Spring Design**, "Artificial Intelligence in ...

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[Limited slip differential recessed spring design - all 2 versions »](#)

 JH Tanser, G Korol, JP Walsh... - *US Patent 5,741,199*, 1998 - [freepatentsonline.com](#)

 Title: Limited slip differential recessed **spring design**. Document Type ... 475/235,

 DIFFERENTIAL **MECHANISM**. ... Belleville springs could have **parallel** abutting conical ...

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 E Morrison - *International Journal of Machine Tools and Manufacture*, 1995 - *Elsevier*

 ... particularly in relation to the flexure **spring design** used on ... a flexure spring based

 traverse **mechanism** was designed ... pick-up in the x direction (**parallel** to the ...

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